Applying Bayesian data analysis to learn about periodic modulations in pulsars

Gregory Ashton<br>Supervisors: Ian Jones \& Reinhard Prix

- Pulsars allow us to study the composition and structure of neutron stars
- Variations in the arrival time of pulsations, often termed timing-noise, tell us that we have unmodelled physics
- There is a lot of variation in the observed timing-noise, but a few show highly periodic variations $\sim 1-10$ yrs

- Today I will discuss two models able to explain these periods


## Periodic modulations: B1828-11

- Demonstrates periodic modulations at 500 days (with harmonics)
- Periodicity observed in: timing-residual, beam-width, frequency, and spin-down rate


Data courtesy of Lyne at al. (2010)

- One explanation for these modulation is precession


## B1828-11: The data

Precession explains the smoothly modulated double-peaked spin-down


However, the beam-width appears to suddenly switch between two states

## Model: Switching

- Lyne et al. (2010): the magnetosphere undergoes sudden periodic switching between two states
- The smooth modulation in the spin-down is due to time-averaging of this underlying spin-down model
- To explain the double-peak, Perera (2014) suggested four times were required

- Lyne (2010) reject precession in favour of 'switching' model

There are arguments for and against both the precession and switching models, but is there enough evidence to rule either out?

## Bayesian data analysis: Model comparison

We would like to quantify how well the two models fit the data. To do this we will use Bayes theorem:

$$
\begin{equation*}
P\left(\mathcal{M}_{j} \mid \mathbf{y}_{\text {obs }}\right)=P\left(\mathbf{y}_{\text {obs }} \mid \mathcal{M}_{j}\right) \frac{P\left(\mathcal{M}_{j}\right)}{P\left(\mathbf{y}_{\text {obs }}\right)} \tag{1}
\end{equation*}
$$

The odds ratio:

$$
\begin{equation*}
\mathcal{O}=\frac{P\left(\mathcal{M}_{A} \mid \mathbf{y}_{\mathrm{obs}}\right)}{P\left(\mathcal{M}_{B} \mid \mathbf{y}_{\mathrm{obs}}\right)}=\frac{P\left(\mathbf{y}_{\mathrm{obs}} \mid \mathcal{M}_{A}\right)}{P\left(\mathbf{y}_{\mathrm{obs}} \mid \mathcal{M}_{B}\right)} \frac{P\left(\mathcal{M}_{A}\right)}{P\left(\mathcal{M}_{B}\right)} \tag{2}
\end{equation*}
$$

If we have no preference for one model or the other then set

$$
\begin{equation*}
\frac{P\left(\mathcal{M}_{A}\right)}{P\left(\mathcal{M}_{B}\right)}=1 \tag{3}
\end{equation*}
$$

and 'let the data speak for itself'

## Bayesian data analysis: Model fitting

For a signal in noise:

$$
\begin{equation*}
y^{\mathrm{obs}}\left(t_{i} \mid \mathcal{M}_{j}, \vec{\theta}\right)=f\left(t_{i} \mid \mathcal{M}_{j}, \vec{\theta}\right)+n\left(t_{i}\right) \tag{4}
\end{equation*}
$$



If the noise is stationary and can be described by a normal distribution:

$$
\begin{equation*}
y^{\mathrm{obs}}\left(t_{i} \mid \mathcal{M}_{j}, \vec{\theta}\right)-f\left(t_{i} \mid \mathcal{M}_{j}, \vec{\theta}\right) \sim N(0, \sigma) \tag{5}
\end{equation*}
$$

Then the Likelihood is:

$$
\begin{equation*}
P\left(y_{i}^{\mathrm{obs}} \mid \mathcal{M}_{j}, \vec{\theta}, \sigma\right)=\frac{1}{\sqrt{2 \pi \sigma^{2}}} \exp \left\{\frac{-\left(f\left(t_{i} \mid \mathcal{M}_{j}, \vec{\theta}\right)-y_{i}\right)^{2}}{2 \sigma^{2}}\right\} \tag{6}
\end{equation*}
$$

We use Markov chain Monte Carlo (MCMC) methods to 'fit' the model to the data. First we check that we have a good fit, then calculate the odds-ratio.

## Precession model:



Switching model:


$$
\frac{P\left(\mathcal{M}_{\text {Precession }} \mid \mathbf{y}_{\text {obs }}\right)}{P\left(\mathcal{M}_{\text {switching }} \mid \mathbf{y}_{\text {obs }}\right)} \approx 1
$$

- We should use data analysis tools to quantify our belief in models
- For the spin-down alone, there is no evidence to suggest switching is preferable to precession
- We now combine the spin-down and beam width date to fully resolve the question
- In the future, we intend to form a hybrid model where the precession biases the switching

